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COMPUTING THE MORDELL-WEIL RANK OF JACOBIANS OF CURVES OF GENUS TWO

DANIEL M. GORDON AND DAVID GRANT

ABSTRACT. We derive the equations necessary to perform a two-descent on the Jacobians of curves of genus two with rational Weierstrass points. We compute the Mordell-Weil rank of the Jacobian of some genus two curves defined over the rationals, and discuss the practicality of using this method.

INTRODUCTION

Let $C$ be a curve of genus two defined over a number field $K$, and $J$ its Jacobian variety. The Mordell-Weil theorem states that $J(K)$ is a finitely-generated Abelian group, but except in a few special cases, it has never been explicitly determined. Recent work of Vojta [24], Faltings [9], and Bombieri [3] relates the number of rational points on $C$ to the rank of $J(K)$, increasing the interest in computing the latter. Further conjectures and results relating $C(K)$ and $J(K)$ can be found in [17 and 23].

In addition, elliptic curves have recently been applied to many computational problems, such as primality testing and factorization [15], and cryptography [14]. There are indications that curves of higher genus have similar uses. They have been proposed for better primality tests [1] and new cryptosystems [13]. However, the lack of explicit knowledge of the properties of these curves has slowed their widespread use. The recent formulations of the group law on the Jacobian by Cantor in [4] and the second author in [11] are a beginning, but more remains to be done.

In this paper we show how to compute the rank of $J(K)$ for a wide class of genus two curves, namely those which have all their Weierstrass points defined over $K$, and whose Jacobians have no two-torsion in their Tate-Shafarevich groups. The former constraint could be removed by performing a Galois descent from $K(J[2])$ to $K$. This would take us too far afield, so we refrain from making this descent now. The latter, however, is a serious constraint, for what we actually compute is the two-Selmer group of $J$.

In principle, it is well known how to compute the Selmer group: much of this work was done by Cassels [6]. One missing ingredient there was the defining equations for $J$, which have now been worked out by Flynn in [10] and the second author in [11]. For computational reasons, more work has to be done.

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beyond that stated in [6]: indeed, it is beneficial to find equations that define
projective models of the homogeneous spaces of J. In the first section we
will give an overview of the descent machinery, paralleling the exposition in
[22 and 5]. In the following section we will present the necessary geometry to
compute the requisite homogeneous spaces. In §3 we outline the method used to
perform computations, and some examples for curves defined over the rationals
are explained in §4.

This research was undertaken while the second author was enjoying the hospi-
tality of Cambridge University.

1. The descent machinery

Let C be a curve of genus two defined over a number field K, all of whose
Weierstrass points are rational over K. Then C has a model of the form
\[ y^2 = (x - a_1)(x - a_2)(x - a_3)(x - a_4)(x - a_5) \]
\[ = x^5 + b_1x^4 + b_2x^3 + b_3x^2 + b_4x + b_5 , \]
where the \( a_i \) (\( i = 1, \ldots, 5 \)) are distinct elements of K. The normalization
of C has one point at infinity, which is rational over K, and which we denote
as \( \infty \). The curve has a hyperelliptic involution \( I \) which maps a point \((x, y)\)
to \((x, -y)\). Let J be the Jacobian variety of C, which we will always take
to be defined by the model given in [11] and described in the next section. We
embed C into J via the divisor class map
\[ P \rightarrow \text{Cl}(P - \infty) , \]
and denote its image by \( \Theta \), a theta divisor. The origin O of J lies on \( \Theta \), and
every point Q on J other than O can be uniquely represented by a divisor
\[ P_1 + P_2 - 2\infty , \]
for some unordered pair of points \( P_1, P_2 \) on C, with \( P_2 \) not equal to \( I(P_1) \).
Note that \( Q \neq O \) lies on \( \Theta \) if and only if \( P_1 \) or \( P_2 \) is \( \infty \). We let U be the
open complement of \( \Theta \) on J.

The group \( J[2] \) of two-torsion points on J has sixteen elements. The
divisors \( 0 \) and \( e_i = a_i - \infty \) (\( 1 \leq i \leq 5 \)) represent the six two-torsion points
which lie on \( \Theta \). The remaining two-torsion points are represented by the
divisors \( e_{ij} = a_i + a_j - 2\infty \) (\( 1 \leq i < j \leq 5 \)). Since the \( a_i \) all lie in K, all the
two-torsion points are \( K \)-rational. Let \( \overline{K} \) be an algebraic closure of K, and let
G be the Galois group of \( \overline{K} \) over K.

Using the exact sequence of Galois modules,
\[ 0 \rightarrow J[2] \rightarrow J(\overline{K}) \rightarrow J(K) \rightarrow 0 , \]
where \( i \) is the natural injection, and \([2]\) the multiplication-by-2 endomorphism,
we get from the long exact sequence of Galois cohomology
\[ 0 \rightarrow J(K)/2J(K) \rightarrow H^1(G, J[2]) \rightarrow H^1(G, J)[2] \rightarrow 0 , \]
(1.1)

Let \( M_K \) be a complete set of inequivalent absolute values on K. For each
\( v \) in \( M_K \), let \( K_v \) denote the localization of K at \( v \). Picking an extension of
\( v \) to \( \overline{K} \) fixes a decomposition group \( G_v \). As before, we get an exact sequence
\[ 0 \rightarrow J(K_v)/2J(K_v) \rightarrow H^1(G_v, J[2]) \rightarrow H^1(G_v, J)[2] \rightarrow 0 . \]
(1.2)
The inclusions $G_v \subseteq G$, $J(K) \subseteq J(K_v)$ give us restriction maps
\[ \text{res}_v : H^1(G, J) \to H^1(G_v, J). \]
The two-Selmer group is defined as
\[ S_2(J/K) = \ker \left\{ H^1(G, J) \overset{\text{res}_v \circ i}{\longrightarrow} \prod_{v \in M_K} H^1(G_v, J) \right\}, \]
and the Tate-Shafarevich group is
\[ \Sha(J/K) = \ker \left\{ H^1(G, J) \overset{\text{res}_v}{\longrightarrow} \prod_{v \in M_K} H^1(G_v, J) \right\}. \]
For all $v \in M_K$ the restriction maps define a map from sequence (1.1) to (1.2), so we get the exact sequence
\[ 0 \to J(K)/2J(K) \overset{\delta}{\to} S_2(J/K) \overset{i}{\to} \Sha(J/K)[2] \to 0. \]
Let $S$ be the finite set of places of $K$ consisting of all the primes at which $J$ has bad reduction, the primes dividing 2, and all the infinite places. Let $H^1(G, J[2]; S)$ denote the subgroup of $H^1(G, J[2])$ consisting of cocycles unramified outside $S$. The proof of the weak Mordell-Weil theorem shows that $H^1(G, J[2]; S)$ is finite, and that it contains $S_2(J/K)$. In our case, since all the two-torsion is rational, $J[2] \cong (\mu_2)^4$ as Galois modules, so we have the Kummer theory isomorphism,
\[ H^1(G, J[2]) \cong (K^*/(K^*)^2)^4, \]
and the isomorphism allows us to identify the classes which are unramified outside $S$. Specifically, $D^4 \cong H^1(G, J[2]; S)$, where
\[ D = \{ x \in K^* | \text{ord}_v(x) \equiv 0 \pmod{2} \forall v \notin S \}/(K^*)^2. \]
Therefore
\[ \delta(J(K)/2J(K)) \subseteq S_2(J/K) \subseteq D^4. \]
We identify $H^1(G, J)$ and $H^1(G_v, J_v)$ with the Weil-Châtelet group of (principal) homogeneous spaces for $J$ over $K$ and $K_v$, respectively. Recall that a homogeneous space represents the trivial class if and only if it has a rational point.
Now for all $v \notin S$, $J[2]$ is an unramified $G_v$ module, so it follows from a theorem of Tate that the image of $H^1(G, J[2]; S)$ in $H^1(G_v, J)$ is zero [19]. Hence we have
\[ S_2(J/K) = \ker \left\{ (D^4) \overset{\text{res}_v \circ i}{\longrightarrow} \prod_{v \notin S} H^1(G_v, J) \right\}. \]
This is how we will compute $S_2(J/K)$—for every element in $D^4$ we compute the corresponding homogeneous space and test to see whether it is locally trivial at all $v$ in $S$. This is an effective procedure which will be described in the following two sections. In many cases, we can identify $J(K)/2J(K)$ with $S_2(J/K)$, and describe $J(K)$ precisely. However, whenever $\Sha(J/K)[2] \neq 0$,
there are homogeneous spaces which are not trivial, yet are everywhere locally trivial.

Remark. Cassels [6] has already made great progress on the problem of computing the rank of the Jacobian of a curve of genus two. He outlined a plan for general curves, with or without rational Weierstrass points, which we will summarize, since it sheds light on our somewhat different approach.

In the case where the Weierstrass points are rational, he computed a map

\[ J(K)/2J(K) \to D^5. \]

The components of the map are given generically for points on \( U \) by

\[(x_1, y_1) + (x_2, y_2) - 2\infty \to (x_1 - a_i)(x_2 - a_i) \pmod{(K^*)^2}, \quad (1 \leq i \leq 5),\]

and for points on \( \Theta \) by

\[(x, y) - \infty \to (x - a_i) \pmod{(K^*)^2}, \quad (1 \leq i \leq 5).\]

The map is determined by its values for \( 1 \leq i \leq 4 \), and it must be modified if any of the points on \( C \) specializes to a Weierstrass point (see [6] or Corollary 2 of the next section).

This almost gives a way to compute the two-Selmer group, once the equations defining \( J \) are known. If \( f_1, \ldots, f_n \) are polynomials which define \( U \), and \( g_1, \ldots, g_m \) are polynomials defining \( C \), then for \( d = (d_1, d_2, d_3, d_4) \) representing an element in \( D^4 \) we can form the auxiliary varieties

\[ F_d : f_j = 0 \quad (1 \leq j \leq n); \quad (x_1 - a_i)(x_2 - a_i) = d_i z_i^2 \quad (1 \leq i \leq 4), \]

and

\[ G_d : g_k = 0 \quad (1 \leq k \leq m); \quad (x - a_i) = d_i z_i^2 \quad (1 \leq i \leq 4). \]

Then \( d \) will be the image of a point in \( J(K)/2J(K) \) (except in the aforementioned special cases) precisely when \( F_d \) or \( G_d \) has a \( K \)-rational solution with \( z_1 z_2 z_3 z_4 \) nonzero. However, it is very hard to test (even locally) whether a number is zero, so for computational reasons, it is expedient to modify this approach.

The problem is that \( F_d \) is birational to but not isomorphic to an open subvariety of a homogeneous space corresponding to \( d \). To remove the condition on \( z_1 z_2 z_3 z_4 \), we need only to take the normalization of \( F_d \) in the extension of \( K(U) \) generated by \( z_1, z_2, z_3 \) and \( z_4 \). But since \( F_d \) is not projective, one must search for rational points instead of integral points. Therefore, we choose in the next section to tackle the problem afresh. This serves the dual purposes of making our argument self-contained from Cassels's approach, and also of showing off some of the beauty of the underlying geometry.

2. Homogeneous spaces

Let \( d = (d_1, d_2, d_3, d_4) \) be a fixed element of \( (K^*)^4 \) representing a class in \( D^4 \). In the last section we defined a map \( i \),

\[ D^4 \cong H^1(G, J[2]; S) \to H^1(G, J) \]

which associates to each \( d \) a cocycle \( i(d) \). The goal of this section is to determine the homogeneous space of \( J \) corresponding to \( i(d) \), which we will denote by \( H(d) \).
Let $Y$ be the pullback of $[2]: J \to J$ along the embedding of $\Theta$ into $J$,

$$
\begin{array}{c}
Y \\
\downarrow^{[2]} \\
\Theta
\end{array}

\begin{array}{c}
C \\
\downarrow \\
J
\end{array}

$$

and let $E$ be its open complement in $J$. We will consider $Y$ as embedded in $J$. Then $Y$ and $E$ are respectively étale covers of $\Theta$ and $U$. We have,

$$
\text{Gal}(E/U) \cong \text{Gal}(Y/C) \cong J[2],
$$

given by defining an automorphism $\sigma_e$ in $\text{Gal}(E/U)$ as the translation-by-$e$ map $T_e: J \to J$ for some $e$ in $J[2]$. If we so choose, we can twist $J$ by twisting $Y$ and $E$ separately to spaces $Y(d)$ and $E(d)$. Equations for these twists are given in Corollary 1 and in the remark following Corollary 2. Testing them separately provides one way to test $H(d)$ for local triviality. But this requires checking for nonintegral local points, which is impractical. We choose instead to give a projective model for $H(d)$ by taking the projective closure of $E(d)$.

The equations defining $E$ are not too difficult to calculate. The underlying geometry is described by Mumford in [20], but we will develop all the explicit material we need in a series of lemmas.

For an affine subvariety $V$ of $J$, we let $A(V)$ denote its ring of regular functions. For a function $f$ on $J$ we let $(f)$ denote its divisor. For a divisor $W$ on $J$, we let $L(W)$ denote the vector space of functions $f$ on $J$ such that $(f) + W$ is effective.

**Lemma 1.** The ring $A(E)$ is generated by $L(Y)$.

**Proof.** The divisor $\Theta$ is symmetric, hence by [21], $Y = [2]*\Theta$ is linearly equivalent to $4\Theta$, which is very ample.

Our tasks, therefore, are first to find a $K$-basis for $L(Y)$, and then to find all the relations among the basis elements. We begin by recalling a set of equations that define $U$.

For a point $z = (x_1, y_1) + (x_2, y_2) - 2\infty$, there are functions defined in [11],

$$
\begin{align*}
X_{22}(z) &= x_1 + x_2, \\
X_{12}(z) &= -x_1x_2, \\
x_{11} &= \frac{X_{22}X_{12}^2 + 2b_1X_{12}^2 - b_2X_{22}X_{12} - 2b_3X_{12} + b_4X_{22} + 2b_5 - 2y_1y_2}{X_{22}^2 + 4X_{12}}, \\
X_{222}(z) &= (y_1 - y_2)/(x_1 - x_2), \\
X_{122}(z) &= (x_1y_2 - x_2y_1)/(x_1 - x_2),
\end{align*}
$$

which are regular on $U$, and generate $A(U)$. It was proven in [11] that

$$
\begin{align*}
g_1: X_{122} &= X_{22}X_{12}^2 - X_{11}X_{12} + b_1X_{12}^2 + b_5, \\
g_2: X_{222} &= X_{22}^2 + X_{12}X_{22} + b_1X_{22}^2 + b_2X_{22} + X_{11} + b_3, \\
g_3: 2X_{12}X_{22} &= 2X_{12}X_{22}^2 - X_{11}X_{22} + X_{12}^2 + 2b_1X_{12}X_{22} + b_2X_{12} + b_4,
\end{align*}
$$

are a set of defining equations for $U$ in five-dimensional affine space.
For notational convenience, we also introduce the following functions from [11]. Set

\[ \begin{align*}
g_4 & : X_{112} = X_{12}X_{222} - X_{22}X_{122}, \\
g_5 & : X_{111} = -X_{11}X_{222} - X_{12}X_{122} + 2X_{22}X_{112} + 2b_1X_{112} - b_2X_{122}, \\
g_6 & : X = \frac{1}{2}(X_{11}X_{22} - X_{12}^2 + b_2X_{12} - b_4).
\end{align*} \]

Then \( g_1, \ldots, g_6 \) define a variety in eight-dimensional affine space isomorphic to \( U \).

For \( 1 \leq i \leq 5 \), define \( h_{e_i}(z) \) by

\[ (2.1) \quad h_{e_i}(z) = -X_{12}(z) - a_iX_{22}(z) + a_i^2 = (x_1 - a_i)(x_2 - a_i). \]

Then \( (h_{e_i}(z)) = 2T_e^*\Theta - 2\Theta \), so automatically \( h_{e_i}([2]z) \) is the square of a function in \( \overline{K}(J) \). In fact, it is a square in \( K(J) \) (see [6, Theorem 4.2]):

**Lemma 2.** For \( 1 \leq i \leq 5 \), there are even functions \( t_{e_i} \) in \( K(J) \), which lie in \( L(Y) \), such that

\[ h_{e_i}([2]z) = (t_{e_i}(z))^2. \]

**Proof.** Let \( w = x - a_i \). Then \( C \) is defined by

\[ y^2 = w^5 + c_1w^4 + c_2w^3 + c_3w^2 + c_4w, \]

for some \( c_1, \ldots, c_4 \) in \( K \). If \( z = (w_1, y_1) + (w_2, y_2) - 2\infty \), then the even function \( h_{e_i}(z) = w_1w_2 \). Suppose that \( P_1 = (w_1, y_1) \) and \( P_2 = (w_2, y_2) \) are independent generic points of \( C \) over \( K \). Then \( P = P_1 + P_2 - 2\infty \) is a generic point of \( J \) over \( K \), and we can compute \([2]P \) as follows. There is a function in \( K(C) \),

\[ g = y - \alpha_1(P)w^3 - \alpha_2(P)w^2 - \alpha_3(P)w - \alpha_4(P), \]

where \( \alpha_1, \ldots, \alpha_4 \) are odd functions in \( K(J) \), such that the divisor of \( g \) is \( 2P + Q \) for some \( Q = (w_3, y_3) + (w_4, y_4) - 2\infty \). Then \([2]P = -Q \), and \( h_{e_i}([2]P) = w_3w_4 \). Now

\[ (\alpha_1w^3 + \alpha_2w^2 + \alpha_3w + \alpha_4)^2 = w^5 + c_1w^4 + c_2w^3 + c_3w^2 + c_4w \]

is a polynomial whose roots (with multiplicity) are \( w_1, w_1, w_2, w_2, w_3 \) and \( w_4 \). Comparing constant terms gives \( w_3w_4 = \alpha_3/\alpha_1 \). Therefore \( h_{e_i}([2]z) \) is the square of the even function \( t_{e_i}(z) = \alpha_4(z)/\alpha_1(z)h_{e_i}(z) \) in \( K(J) \).

Now for any \( 1 \leq i < j \leq 5 \), we define \( t_{e_{ij}}(z) \) by the relation

\[ (2.2) \quad X_{112}([2]z) + (a_i + a_j)X_{122}([2]z) + a_ia_jX_{222}([2]z) = t_{e_i}(z)t_{e_j}(z)t_{e_{ij}}(z). \]

Since \( X_{112}, X_{122}, X_{222} \) are odd and \( t_{e_i}, t_{e_j} \) are even, \( t_{e_{ij}} \) is an odd function. Squaring (2.2) and using \( g_1, g_2, g_3, g_4 \) and (2.1) gives us the relation

\[ (2.3) \quad h_{e_{ij}}([2]z) = (t_{e_{ij}}(z))^2, \]

where

\[ h_{e_{ij}}(z) = X_{11}(z) - X_{11}(e_{ij}) + (a_i + a_j)X_{12}(z) + a_ia_jX_{22}(z), \]

so \( t_{e_{ij}} \) is in \( K(J) \), and \( L(Y) \) as well. It follows from the group law in [11] that \( h_{e_{ij}}(z) \) has divisor \( 2T_{e_{ij}}^*\Theta - 2\Theta \). We will soon prove that \( 1, t_{e_i} \ (1 \leq i \leq 5), t_{e_{ij}} \ (1 \leq i < j \leq 5) \) form a \( K \)-basis for \( L(Y) \). We first need to describe the action of \( \text{Gal}(E/U) \) on these functions, which is given via the Weil pairing [21].
Since $J$ is principally-polarized, we can define the Weil pairing on $J[2]$ as a map

$$w : J[2] \times J[2] \to \mu_2,$$

given as in [21]. For $O$ in $J[2]$ we define $h_O = t_O = 1$. Then for any $e$ in $J[2]$ we have $(h_e(z)) = 2T^e \Theta - 2\Theta$, and $h_e([2]z) = (t_e(z))^2$, so $w(e', e'')$ for $e', e''$ in $J[2]$ is given by

$$(2.4) \quad w(e', e'') = \frac{t_{e'}(z + e'')}{t_{e'}(z)},$$

for those $z$ in $J$ for which $(2.4)$ is defined. The pairing is bilinear, nondegenerate, and $w(e, e) = 1$ for all $e$ in $J[2]$. Therefore the pairing is alternating, and since it takes its values in $\mu_2$, it is also symmetric.

**Lemma 3.** Let $i, j, k$ be distinct elements of $\{1, 2, 3, 4, 5\}$. Then

(a) $w(e_i, e_{jk}) = 1$,

(b) $w(e_i, e_j) = -1$.

**Proof.** The divisor of $t_{e_i}(z)$ is $[2]^{-1}(T_{e_i}^e \Theta - \Theta)$. Since $e_{jk}$ is not contained in the support of $T_{e_i}^e \Theta - \Theta$, we can pick a $z'$ in $[2]^{-1}e_{jk}$ so that $(2.4)$ is defined at $z'$. Since $z' + e_{jk} = -z'$, and $t_{e_i}$ is even, we get $w(e_i, e_{jk}) = 1$, establishing (a). By bilinearity, $w(e_i, O) = 1$, and $w(e_i, e_i) = 1$, so we have found eight elements $e$ of $J[2]$ such that $w(e_i, e) = 1$. Since the pairing is nondegenerate, $w(e_i, e_j) = -1$, establishing (b). Alternatively, one can compute the pairing by evaluating functions on the curve, see [2, p. 283].

For any $e''$ in $J[2]$, we define a character on $J[2]$ by

$$\chi_{e''}(e') = w(e', e'').$$

Then the action of $\text{Gal}(E/U)$ is given by

$$\sigma_e(t_{e''}) = w(e'', e')t_{e''} = w(e', e'')t_{e''} = \chi_{e''}(e')t_{e''}.$$

By the nondegeneracy of the Weil pairing, these are precisely the 16 distinct characters of order dividing 2 on $J[2]$.

**Lemma 4.** The vector space $L(Y)$ has a $K$-basis given by the functions

$$1, t_{e_i} \quad (1 \leq i \leq 5), \quad \text{and} \quad t_{e_{ij}} \quad (1 \leq i < j \leq 5).$$

**Proof.** We have already shown that the functions are in $L(Y)$. Since the 16 functions are all in different isotypical components for the action of $\text{Gal}(E/U)$ on $L(Y)$, they are linearly independent.

We will prove that $t_{e_1}, t_{e_2}, t_{e_3}, t_{e_4}, t_{e_{13}}, t_{e_{25}}, t_{e_{35}},$ and $t_{e_{45}}$ generate $L(Y)$ as a $K$-algebra. First we need to derive some relations among the variables. As a convention we will let $i, j, k$ denote any three elements of the set $\{1, 2, 3, 4, 5\}$, and let $l$ and $m$ stand for the complementary elements.

**Lemma 5.**

$$(2.5) \quad t_{e_{ij}}(z)t_{e_k}(z)t_{e_{jk}}(z) = X_{111}([2]z) + (a_i + a_j + a_k)X_{112}([2]z) + (a_ia_j + a_ia_k + a_ja_k)X_{122}([2]z) + a_ia_ja_kX_{222}([2]z),$$
\[ t_{e_i}(z) t_{e_{j,k}}(z) t_{e_{l,m}}(z) = -X([2]z) + a_iX_{11}([2]z) \]
\[ + (a_j a_k + a_i a_{m_1} + a_j(a_j + a_k + a_i + a_m))X_{12}([2]z) \]
\[ + a_i(a_j a_k + a_i a_m)X_{22}([2]z) \]
\[ - a_i(a_j a_k a_l + a_i a_k a_m + a_i a_l a_m + a_k a_i a_m + a_i(a_j a_m + a_j a_k)). \]

**Proof.** Using \( g_1, \ldots, g_6 \) and Lemma 2, one can verify that (2.5) follows from multiplying together (2.2) for each of \( (i, j), (i, k), (j, k) \) and then dividing by (2.1) for \( i, j, \) and \( k \). Likewise (2.6) follows from multiplying (2.2) for each of \( (j, k) \) and \( (l, m) \) and (2.1) for \( i, \) and then dividing by \( y_1 y_2([2]z) = t_{e_i}(z) t_{e_j}(z) t_{e_k}(z) t_{e_l}(z) t_{e_m}(z) \) (which can be derived from the definition of \( X_{11} \)). In fact, both these relations were discovered by using the analytic theory of the Jacobian as outlined in [11].

**Lemma 6.** We have six types of equations:

**Type I** \((i, j, k)\): 
\[
(a_j - a_i) t_{e_{j,k}}^2 + (a_i - a_k) t_{e_{i,j}}^2 + (a_k - a_j) t_{e_{i,k}}^2
= (a_j - a_i)(a_k - a_i)(a_k - a_j).
\]

**Type II** \((i, j, k)\): 
\[
t_{e_{i,j}}^2 - t_{e_{i,k}}^2 = (a_k - a_j)(t_{e_{i,j}}^2 - (a_i - a_k)(a_i - a_m)).
\]

**Type III** \((i, j, l, m)\): 
\[
t_{e_{i,j}}t_{e_{i,m}} - t_{e_{i,j}}t_{e_{j,m}} = (a_j - a_i)t_{e_{i,j}}t_{e_{i,m}}.
\]

**Type IV** \((i, j, k, l, m)\): 
\[
t_{e_{i,j}}t_{e_{j,k}} - t_{e_{i,j}}t_{e_{k,l}} = (a_i - a_j)t_{e_{i,j}}t_{e_{k,l}}.
\]

**Type V** \((i, j, k, l, m)\): 
\[
t_{e_{i,j}}t_{e_{j,m}} - t_{e_{i,j}}t_{e_{k,l}} = (a_i - a_m)(a_l - a_k)t_{e_{i,j}}.
\]

**Type VI** \((i, j, k, l)\): 
\[
(a_j - a_k)t_{e_{i,j}}t_{e_{i,l}} + (a_k - a_i)t_{e_{i,j}}t_{e_{i,k}} + (a_i - a_j)t_{e_{i,l}}t_{e_{i,k}} = 0.
\]

**Proof.** Type I: Take (2.1) and Lemma 2 for \( i, j, \) and \( k, \) and eliminate \( X_{12} \) and \( X_{22} \).

Type II: Take (2.3) for \( (i, j) \) and \( (i, k) \) and eliminate \( X_{11} \). This gives a multiple of (2.1) for \( i \) plus a constant. Then apply Lemma 2.

Type III: Take (2.5) with \( (i, l, m) \) and \( (j, l, m) \) to eliminate \( X_{111} \). This leaves a multiple of (2.2) for \( (l, m) \).

Type IV: Take (2.6) for \( (i, j, k, l, m) \) and \( (j, i, k, l, m) \) and eliminate \( X \). This gives a multiple of (2.3) for \( (l, m) \).

Type V: Take (2.6) for \( (i, j, k, l, m) \) and \( (i, j, k, l, m) \) and eliminate \( X \). This gives a multiple of (2.1) for \( i \). Then apply Lemma 2.

Type VI: Take (2.2) for \( (i, l), (j, l) \) and \( (k, l) \), and eliminate \( X_{122} \) and \( X_{222} \) using the definition of \( X_{112} \). Then divide by \( t_{e_{i,j}} \).

We will also need an equation of Type VII:

\[
\text{VII}(i, j, k, l): t_{e_{i,j}}^2(a_k - a_j) + t_{e_{i,k}}^2(a_i - a_k) + t_{e_{i,l}}^2(a_j - a_i)
= (a_j - a_i)(a_k - a_i)(a_k - a_j)(a_l - a_m),
\]

which is a linear combination of \( \Pi(i, j, k) \) and \( \Pi(i, i, k) \).

Let \( T \) denote the set \( \{t_{e_{i,j}}, t_{e_{i,k}}, t_{e_{i,l}}, t_{e_{j,k}}, t_{e_{j,l}}, t_{e_{k,l}}\} \).

**Proposition 1.** The ring \( A(E) \cong K[T]/R \), where \( R \) is the ideal of relations generated by: \( I(1, 2, 3), I(1, 2, 4), VI(1, 2, 3, 5), VI(1, 2, 4, 5), VII(1, 2, 3, 5), \) and \( VII(1, 2, 4, 5) \).

A smooth model for \( E \) in eight-dimensional affine space is given by these six equations.
Proof. First we note that $L(Y)$ is contained in the algebra generated by $T$. Indeed, $IV(k, l, 5, i, j)$ for $1 \leq i < j \leq 4$ shows that $te_{ij}$ are in the algebra, and then $V(5, 1, 2, 3, 4)$ shows that $te_5$ is in it, as well.

Since $E$ is the pullback of $U$ under $[2]$, its affine ring is the normalization of $K(U)$ in the field gotten by adjoining $T$. Since the normalization is unique, and nonsingular varieties are normal, it suffices to show that the Jacobian matrix $M$ of the six equations generating $R$ with respect to $T$ has rank 6 at all points of $E$.

Suppose that two or more of the variables in $T$ are zero. This only happens at points of $E$ which cover a two-torsion point $e$ on $U$. Since $I(1, 3, 4)$, $I(2, 3, 4)$, $VI(1, 3, 4, 5)$, $VI(2, 3, 4, 5)$, $VI(1, 3, 4, 5)$, $VII(2, 3, 4, 5)$ are easily seen to be in $R$, there is a symmetry among the variables of $T$ gotten by permuting the indices $\{1, 2, 3, 4\}$. So we need only check two possibilities, that $e$ is $e_{12}$ or $e_{15}$.

When $e = e_{12}$, $te_{e_1} = te_{e_2} = te_{e_3} = te_{e_4} = 0$, and all the other variables in $T$ are nonzero. In this case, it is not hard to find the six-by-six minor in $M$ which has a nonvanishing determinant.

When $e = e_{15}$, $te_{e_1} = te_{e_5} = 0$, and all the other variables in $T$ are nonzero. The variables $te_{e_2}, te_{e_3}$, and $te_{e_4}$ are nonzero as well. In this case, two columns of $M$ contain all zeroes, so there is only one six-by-six minor, $N$, whose determinant could be nonvanishing. A calculation using equations of Type V shows that the determinant is

$$16(a_1 - a_2)(a_1 - a_3)(a_1 - a_4)(a_2 - a_3)(a_2 - a_4)(a_3 - a_4)te_{e_1}te_{e_2}te_{e_3}te_{e_4},$$

which is nonzero.

Finally, if one or none of the variables in $T$ is zero, then $te_{e_i}te_{e_j}te_{e_k}$ must be nonzero for some permutation $(i, j, k, l)$ of $\{1, 2, 3, 4\}$. By symmetry, we can assume $(i, j, k, l) = (1, 2, 3, 4)$, and so again the determinant of $N$ is nonzero.

We are now almost in a position to find the equations defining $E(d)$, the twist of $E$ by the cocycle $i(d)$. First we must describe the cocycle $i(d)$ precisely.

The Kummer theory isomorphism from $K^*/(K^*)^2$ to $H^1(G, \mu_2)$ is defined by taking a nonzero $k$ in $K$ and assigning to it the quadratic character $\chi_k$ on $G$ defined by $\chi_k(g) = g(\sqrt{k})/\sqrt{k}$. Let $\psi: \mu_2 \cong \mathbb{Z}/2\mathbb{Z}$.

**Lemma 7.** For every $d = (d_1, d_2, d_3, d_4)$ in $D^4$, the cocycle $i(d)$ in $H^1(G, J)$ is given by $g \rightarrow a_g$, where

$$a_g = \psi(\chi_{d_1}(g))e_1 + \psi(\chi_{d_2}(g))e_2 + \psi(\chi_{d_3}(g))e_3 + \psi(\chi_{d_4}(g))e_4.$$

**Proof.** Using Lemma 3 and the Weil pairing, we see that $e_i$, $i = 1, 2, 3, 4$, gives a $\mathbb{Z}/2\mathbb{Z}$-basis for $J[2]$. Given this choice of basis, the lemma now follows by identifying $H^1(G, J[2]) \cong H^1(G, \mathbb{Z}/2\mathbb{Z})^4 \cong H^1(G, \mu_2)^4$, and mapping the cocycle into $H^1(G, J)$.

To perform the twist, we use the isomorphism

$$J[2] \cong \text{Gal}(E/U)$$

to induce an action of $G$ on $A(E)$ via $i(d)(g)$. We must determine which functions in $K(E)$ are invariant under $G$.

Recall that $d = (d_1, d_2, d_3, d_4) \in (K^*)^4$ is a fixed representative for a class in $D^4$. We will now let $d_5$ be a fixed element in $K^*$ such that $d_5 \equiv d_1d_2d_3d_4$
mod \((K^*)^2\). To make this choice explicit, we will often abuse notation and write \(d = (d_1, d_2, d_3, d_4, d_5)\) for the corresponding element in \(D^5\). We can now define an involution on \(D^4\) by picking \(d^* = (d_1^*, d_2^*, d_3^*, d_4^*)\) to be a fixed element in \((K^*)^4\) representing \((d_5/d_1, d_5/d_2, d_5/d_3, d_5/d_4)\). Note that the map is an involution since \(d_i^* = d_i^*d_i^*d_i^*d_i^*d_i^* = d_i^*d_i^*d_i^*d_i^*d_i^*d_i^* d_i d_3 d_4 \equiv d_5 \mod (K^*)^2\).

Let \(\sqrt{d_i^*}\) \((1 \leq i \leq 5)\) denote a fixed choice for the square root of \(d_i^*\).

**Lemma 8.** The functions of \(\overline{K}(E)\) which are invariant under the action of \(i(d)\) are generated over \(K\) by

\[
z_i = t_{e_i}/\sqrt{d_i^*}, \quad (1 \leq i \leq 5),
\]

and

\[
z_{ij} = t_{e_i}/\sqrt{d_i^*} \sqrt{d_j^*}, \quad (1 \leq i < j \leq 5).
\]

**Proof.** If \(g\) is in \(G\), then by Lemma 7, for any \(e \in J[2]\),

\[
g(t_e) = \sigma_{a_e} t_e = \left( \prod_{1 \leq i \leq 4} w(\psi(\chi_{d_i}(g)) e_i, e) \right) t_e
\]

\[
= \left( \prod_{1 \leq i \leq 4} w(e_i, e)^\psi(\chi_{d_i}(g)) \right) t_e.
\]

Now by Lemma 3, if \(e = e_j\) for \(1 \leq j \leq 4\),

\[
g(t_{e_j}) = \left( \prod_{i \neq j} \chi_{d_i}(g) \right) t_e = \chi_{d_i^*}(g) t_{e_j}.
\]

If \(e = e_5\), then

\[
g(t_5) = \left( \prod_{1 \leq i \leq 4} \chi_{d_i}(g) \right) t_e = \chi_{d_5^*}(g) t_{e_5}.
\]

Since \(g(\sqrt{d_i^*}) = \chi_{d_i^*}(g) \sqrt{d_i^*}\), for any \(1 \leq i \leq 5\), \(z_i\) is \(G\)-invariant. Likewise, if \(e = e_{ij}\) for \(1 \leq i < j \leq 4\), then

\[
g(t_{e_{ij}}) = \chi_{d_i}(g) \chi_{d_j}(g) t_{e_{ij}} = \chi_{d_i^* d_j^*}(g) t_{e_{ij}},
\]

and if \(1 \leq i \leq 4\),

\[
g(t_{e_5}) = \chi_{d_5}(g) t_{e_5} = \chi_{d_i^* d_j^*}(g) t_{e_5},
\]

hence \(z_{ij}\) is also \(G\)-invariant. Since \(K(E)\) is generated over \(K\) by \(t_{e_i}\) \((1 \leq i \leq 5)\), and \(t_{e_{ij}}\) \((1 \leq i < j \leq 5)\), the \(z_i\) \((1 \leq i \leq 5)\), and \(z_{ij}\) \((1 \leq i < j \leq 5)\), generate a field \(K_d\) over \(K\) which is isomorphic over \(\overline{K}\) to \(\overline{K}(E)\). Hence \(K_d\) is the function field of the twist of \(E\) by \(i(d)\), and therefore it is also the field of all \(G\)-invariant functions of \(\overline{K}(E)\).
Corollary 1. A smooth model for $E(d^*)$ in eight-dimensional affine space is given by

\[
(a_2 - a_1)d_3z_3^2 + (a_1 - a_3)d_2z_2^2 + (a_3 - a_2)d_1z_1^2 \\
= (a_2 - a_1)(a_3 - a_1)(a_3 - a_2), \\
(a_2 - a_1)d_4z_4^2 + (a_1 - a_4)d_2z_2^2 + (a_4 - a_2)d_1z_1^2 \\
= (a_2 - a_1)(a_4 - a_1)(a_4 - a_2), \\
(a_2 - a_3)d_1z_1z_3 + (a_3 - a_1)d_2z_2z_2 + (a_1 - a_2)d_3z_3z_3 = 0, \\
(a_2 - a_4)d_1z_1z_4 + (a_4 - a_1)d_2z_2z_4 + (a_1 - a_2)d_4z_4z_4 = 0, \\
d_1d_5z_5^2(a_3 - a_2) + d_2d_5z_5^2(a_1 - a_3) + d_3d_5z_5^2(a_2 - a_1) \\
= (a_2 - a_1)(a_3 - a_1)(a_3 - a_2)(a_5 - a_4), \\
d_1d_5z_5^2(a_4 - a_2) + d_2d_5z_5^2(a_1 - a_4) + d_4d_5z_5^2(a_2 - a_1) \\
= (a_2 - a_1)(a_4 - a_1)(a_4 - a_2)(a_5 - a_3).
\]

Proof. These equations are gotten by twisting those listed in Proposition 1 and replacing $d$ by $d^*$. These equations clearly define a variety which is isomorphic to $E$ over $K$.

Theorem 1. Let $s = \sqrt{d_1}\sqrt{d_2}\sqrt{d_3}\sqrt{d_4}\sqrt{d_5}$. A smooth, projective model for $H(d^*)$ is given by the following 72 equations

\[
I(d^*)(z): (a_j - a_i)d_kz_i^2 + (a_i - a_k)d_jz_j^2 + (a_k - a_j)d_iz_i^2 \\
= (a_j - a_i)(a_k - a_i)(a_k - a_j)z_0^2,
\]

where $(i, j, k) = (1, 2, 3), (1, 2, 4), (1, 2, 5)$.

\[
II(d^*)(z): d_1d_jz_i^2 - d_1d_kz_i^2 = (a_k - a_j)(d_i^2 - (a_i - a_1)(a_i - a_m)z_0^2),
\]

where $(i, j, k) = (1, 2, 3), (1, 2, 4), (1, 2, 5), (2, 1, 3), (2, 1, 4), (2, 1, 5), (3, 1, 4), (3, 1, 5), (4, 1, 5)$.

\[
III(d^*)(z): d_1z_iz_m - d_jz_jz_m = (a_j - a_i)z_1z_m,
\]

where $\{l, m\}$ is any pair of indices, and $\{i, j\}$ is taken in turn to be any two pairs chosen from the remaining three indices.

\[
IV(d^*)(z): s(z_iz_j - z_iz_j) = (a_i - a_j)d_mz_mz_0,
\]

where $\{l, m\}$ is any pair of indices, and $\{i, j\}$ is taken in turn to be any two pairs chosen from the remaining three indices.

\[
V(d^*)(z): s(z_iz_jz_m - z_iz_jz_m) = (a_i - a_m)(a_i - a_k)d_iz_iz_0,
\]

where $i$ is any index, and $\{\{j, k\}, \{l, m\}\}$ is taken in turn to be any two partitions of the remaining four indices into pairs.

\[
VI(d^*)(z): (a_j - a_k)d_1z_i + (a_k - a_l)d_1z_j + (a_i - a_j)d_kz_lz_k = 0,
\]

where $l$ is any index, and $\{i, j, k\}$ is taken in turn to be any two triplets chosen from the remaining four indices.

These give a minimal set of defining equations for the embedding determined by $L(Y(d^*))$.

Proof. Let $V(d^*)$ be the variety defined by these 72 equations. The first thing that we note is that the affine open subvariety $V_0$ defined by $z_0 \neq 0$ is isomorphic to $E(d^*)$. Indeed, all the equations in Corollary 1 are gotten from the 72
by eliminating \( z_5 \). Conversely, in Proposition 1 we showed that \( z_5, z_{12}, z_{13}, z_{14}, z_{23}, z_{24}, \) and \( z_{34} \) are elements in the algebra generated by the eight coordinate functions given in Corollary 1. So by Lemmas 6 and 8, all 72 equations in the statement of the theorem are homogenizations of those contained in the ideal generated by those in Corollary 1. It now suffices to show that these 72 equations define the projective closure of \( V_0 \). It is enough to show that each element of the open cover

\[
V_0, V_i = (z_i \neq 0), \quad (1 \leq i \leq 5), \quad V_{ij} = (z_{ij} \neq 0) \quad (1 \leq i < j \leq 5)
\]

is a nonsingular variety. In (1.1) we defined a map \( \delta: J(K)/2J(K) \to D^4 \). Let \( \delta_i = \delta(e_i), \delta_{ij} = \delta(e_{ij}) \). The theorem will follow from the establishment of the following claim:

**Claim.** \( V_i \) is isomorphic to a nonsingular model of \( E(d^*\delta_i) \), and \( V_{ij} \) is isomorphic to a nonsingular model of \( E(d^*\delta_{ij}) \).

For the moment, we will think of \( H(d^*) \) as the twist of \( J \) by a cocycle in \( H^1(G, J[2]) \). In [5], Cassels equates \( H^1(G, J[2]) \) with equivalence classes of "\( \lambda \)-coverings" (here \( \lambda \) is the [2]-map). There he produces a diagram

\[
\begin{array}{ccc}
J & \xrightarrow{\theta_{d^*}} & H(d^*) \\
\downarrow & & \downarrow \lambda \\
J & \xleftarrow{\Lambda} & \\
\end{array}
\]

where \( \Lambda \) is defined over \( K \), and \( \theta_{d^*} \) is an isomorphism defined over \( \overline{K} \). He also shows that for \( P \in J(K) \), there is a \( K \)-rational map

\[
\phi(P): H(d^*) \to H(d^*\delta(P))
\]

defined by the commutativity of

\[
\begin{array}{ccc}
J & \to & J \\
\downarrow \theta_{d^*} & & \downarrow \theta_{d^*\delta(P)} \\
H(d^*) & \xrightarrow{\phi(P)} & H(d^*\delta(P))
\end{array}
\]

where \( T_P \) denotes the translation-by-\( P \) map. We will prove the first part of the claim by considering the map \( \phi_i = \phi(e_i) \); indeed we will compute the effect of \( \phi_i \) on every coordinate functions of \( V(d^*) \). We will let small letters denote functions on \( V(d^*) \) and will use capital letters to denote those on \( V(d^*\delta_i) \). By comparing divisors, we can see that up to constants \( c_0, c_i, c_j, c_{ij}, c_{jk} \), the map must be defined by

\[
(2.7) \quad \phi_i(z_0) = c_0 z_i, \quad \phi_i(z_i) = c_i z_0, \quad \phi_i(z_j) = c_j z_{ij}, \quad \phi_i(z_{ij}) = c_{ij} z_j, \quad \phi_i(z_{jk}) = c_{jk} z_{ijm},
\]

for \( i \neq j \neq k \neq i \), and \( l, m \) complementary to \( i, j, k \) in \( \{1, 2, 3, 4, 5\} \). We can compute the constants by evaluating (2.7) at carefully-chosen two-torsion points. The twist is uniquely determined by the condition that \( \phi_i \) is defined over \( K \), so we can compute the constants and the twist simultaneously.
The computation shows that \( c_0 = 1, \ c_i = d_i, \ c_j = (a_j - a_i)d_j, \ c_{ij} = d_id_j, \) and 
\[ c_{jk} = d_jd_k, \] with \( d^*\delta_i = \Delta = (\Delta_1, \Delta_2, \Delta_3, \Delta_4, \Delta_5) \) defined by
\[ \Delta_j = d_j(a_i - a_j), \quad \text{for} \ i \neq j, \quad \text{and} \quad \Delta_i = d_i \prod_{j \neq i}(a_i - a_j). \]

Let fixed square roots \( \sqrt{\Delta_i} \) be chosen so that
\[ \prod_{1 \leq i \leq 5} \sqrt{\Delta_i} = s \prod_{i \neq j}(a_i - a_j). \]

It is then straightforward to verify that every equation of Types I-VI \((d^*)(z)\) gets transformed under \( \phi_i \) into a linear combination of equations of Types I-VI \((\Delta)(Z)\), and that \( V_i \) gets mapped into \((Z_0 \neq 0) \equiv E(\Delta)\). Replacing \( d^* \) by \( d^*\delta_i \) gives an inverse map to \( \phi_i \), hence we get the desired isomorphism. The second part of the claim now follows from the first by replacing \( d^* \) by \( d^*\delta_j \), and considering the composite \( \phi(e_{ij}) = \phi_i\phi_j \).

We have shown that 72 relations among 136 monomials serve to generate all the relations for the homogeneous coordinate ring of \( H(d^*) \). Setting \( z_0 = 1 \) specializes each of the monomials to a function in \( L(2Y(d^*)) \). But this space has dimension 64, since \( 2Y \) is linearly equivalent to \( 8\Theta \). Therefore no fewer than 72 relations suffice to generate all relations.

Remark. Setting \( d = (1, 1, 1, 1, 1) \), \( s = 1 \), we recover in our special case a projective transformation of the equations discovered by Flynn [10], who placed no rationality restrictions on the Weierstrass points of \( C \). See also [7].

We can now rederive the explicit form of the map (1.3) given in [6] and verify that it agrees with (1.1)

**Corollary 2.** (1) \( \delta_i = \delta(e_i) = (\Delta_1, \Delta_2, \Delta_3, \Delta_4, \Delta_5) \) where
\[ \Delta_j = (a_i - a_j), \quad \text{for} \ i \neq j, \quad \text{and} \quad \Delta_i = \prod_{j \neq i}(a_i - a_j). \]

(2) For \( P \in J(K) \), let \( \delta(P) = (P_1, P_2, P_3, P_4, P_5) \). If \( P = (x_1, y_1) + (x_2, y_2) - 2\infty \) is in \( U \), then for \( 1 \leq j \leq 5 \),
\[ P_j \equiv (x_1 - a_j)(x_2 - a_j) \quad (\text{mod} \ (K^*)^2), \quad \text{if} \ x_1 \neq a_j, \ x_2 \neq a_j, \]
and if \( P = (x, y) - \infty \) is on \( \Theta \) with \( x \neq a_j \),
\[ P_j \equiv (x - a_j) \quad (\text{mod} \ (K^*)^2). \]

By linearity, this determines \( \delta(P) \) for all \( P \in J(K) \).

**Proof.** Statement (1) follows directly from the proof of the theorem by setting \( d = (1, 1, 1, 1, 1) \). To establish (2), let \( P \) be in \( J(K) \), and \( P = [2]Q \) for some \( Q \in J(K) \). We can think of \( H(\delta(P)) \) as the twist of \( J \) corresponding to the cocycle \( \beta_g \) in \( H^1(G, J[2]) \) defined by \( \beta_g = g(Q) - Q \) for \( g \in G \). Since \( g(Q) = Q + \beta_g \), it follows immediately from the corresponding \( \lambda \)-covering
\[
\begin{array}{ccc}
J & \xrightarrow{\theta_{\delta(P)}} & H(\delta(P)) \\
\downarrow{[2]} & & \\
J & \xrightarrow{\lambda} & \\
\end{array}
\]
that \( \theta_{\delta}(P) \) is \( K \)-rational. But for \( P \) on \( U \), \( \Lambda \) is given by Lemmas 2 and 8. So if \( P = (x_1, y_1) + (x_2, y_2) - 2\infty \), with \( x_1 \neq a_j \), \( x_2 \neq a_j \), then

\[
(x_1 - a_j)(x_2 - a_j) = -X_{12}(P) - a_jX_{22}(P) + a_j^2 = P_jz_j(Q)^2,
\]

with \( z_j(Q) \in K^* \). If \( x_1 \) or \( x_2 \) is \( a_j \), then by linearity and (1) we can reduce to the case that \( P \) is on \( \Theta \). Now if \( P \) is on \( \Theta \), and \( P \in J[2] \), \( \delta(P) \) is given by (1). Finally, if \( P \) in on \( \Theta \), and \( P \notin J[2] \), then the corollary follows by linearity and (1) after computing \( \delta(P + e_k) \) for some \( k \neq j \).

**Remark.** The twists of \( Y(d^*) \) are easy to calculate—these are essentially the heterogeneous spaces discussed in [8]. We include them for completeness and omit their derivation.

A nonsingular model for \( Y(d^*) \) in five-dimensional projective space is given by

\[
d_5z_5^2 - d_iz_i^2 = (a_i - a_5)z_5^2,
\]

for \( i = 1, 2, 3, 4 \).

## 3. Calculating the rank over \( Q \)

Suppose now that the curve \( C \) is defined over the rational numbers \( Q \). Then we can find a model \( y^2 = q(x) \) for \( C \), where \( q(x) \) is a monic quintic in \( Z[x] \). For each \( d \in D^4 \), we need to determine whether the 72 equations of Theorem 1 defining \( H(d^*) \) have a solution over \( Q \). To check the space for everywhere local triviality, it suffices to test for solutions over the real numbers \( R \) and over the \( p \)-adic numbers \( Q_p \) for each prime \( p \) of bad reduction. If \( H(d^*) \) has solutions over these local fields, then either a global rational solution exists, or the space is an element of order two in the Tate-Shafarevich group.

Since the map \( \delta \) defined in \( \S 1 \) is a homomorphism, we need only consider cosets of the known rational points. For any curve with rational Weierstrass points, we have sixteen spaces corresponding to the torsion points on \( J \). Sometimes when a new rational point on \( J \) is discovered, the coset of rational points doubles in size, and the number of spaces which must be tested is cut in half.

It is easiest to test for real solutions. The answer depends only on the signs of \( d_1, d_2, d_3, d_4 \), so there are only 16 sign configurations to investigate. Suppose that the \( a_i \)'s are given in increasing order. Checking the signs of the coefficients of the Type I and II equations shows that each have solutions over \( R \) for only 14 of these configurations. Combining these constraints shows that the only possible signs for the \( d_1, d_2, d_3, d_4 \) are

\[
(+, -, -, -), \quad (+, -, -, +), \quad (+, +, +, -), \quad (+, +, +, +).
\]

This immediately eliminates three-fourths of the homogeneous spaces. Looking at the spaces corresponding to \( J[2] \) shows that the remaining one-quarter spaces do indeed have real solutions.

Since \( H(d^*) \) is projective, to search for solutions over \( Q_p \), we need only search each part of an affine cover for \( p \)-adic integral solutions. By Hensel's lemma, this reduces to a finite amount of work, for then it suffices to search for solutions in \( Z/p^rZ \) for some sufficiently large \( r \). However, this is a formidable task. While it is often possible to perform a two-descent on elliptic curves by
hand, it is not feasible to do the same for the Jacobians of curves of genus two with this method. Even with a computer, the tests must be organized efficiently, using faster, weaker tests at first, and only then going onto stronger, more time-consuming tests when the remaining set of homogeneous spaces has been pruned to a reasonable number.

To minimize \( r \), we will always assume that \( d_1, d_2, d_3, d_4, \) and \( d_5 \) are squarefree integers. Further, we rescale each equation to make sure that every coefficient is a \( p \)-adic integer, with at least one coefficient being a unit. Even with these precautions, with sixteen variables, exhaustive tests modulo primes larger than two are infeasible.

However, there are ways to reduce the number of cases which have to be examined. For instance, the Type I equations involve only the variables \( z_0, z_1, z_2, z_3, z_4, \) and \( z_5 \). For many possible assignments of these variables \((\mod p^r)\) there will be no solution to the Type I equations, so \( H(d^*) \) may be eliminated without considering the other ten variables.

Also since the function field of \( J \) is generated by only a few variables (for example, by \( z_1, z_2, z_3, z_4, \) and \( z_12 \)), once the assignment of a few variables are made, others are determined. This could involve dividing by \( p \), but in practice, not too many assignments have to be made before the others are determined. To automate this process, it proved convenient to consider the cases \( z_0 \not\equiv 0 \pmod{p} \) and \( z_0 \equiv 0 \pmod{p} \) separately (the latter correspond to points on \( Y(d^*) \)).

In the examples we now present, checking each homogeneous space using the tests over \( \mathbb{R} \), checking the full set of equations \((\mod p)\) for each of the primes of bad reduction, and considering the Type I equations \((\mod p^2)\) were sufficient to eliminate all of the homogeneous spaces without solutions over \( \mathbb{Q} \), and could be done in a reasonable amount of time.

4. SOME EXAMPLES

Let \( C \) be a curve of genus two defined over \( \mathbb{Q} \) with rational Weierstrass points. Suppose that \( C \) has bad reduction at primes \( p_1, p_2, \ldots, p_k \). Then there are \( k + 1 \) places in \( S \), and \( 2^{4k+4} \) homogeneous spaces which need to be tested for local-triviality. For \( k = 3 \), there are 65,536 spaces, which in our examples were tested on a SUN Sparcstation in a few hours. For \( k = 4 \), there are 1,048,576 spaces, which could be done in a reasonable amount of time on a larger computer. The size of the primes of bad reduction also has a large effect on the running time.

Since the Weierstrass points are rational, the curve necessarily has bad reduction at 2 and at 3. In our examples, comparatively quick tests \((\mod 2)\) and \((\mod 3)\) and \((\mod 4)\) and \((\mod 9)\) on the Type I equations eliminated the vast majority of the spaces.

We give two examples of the method

**Theorem 2.** Let \( C \) be the curve

\[ y^2 = x(x - 1)(x - 2)(x - 5)(x - 6), \]

and \( J \) its Jacobian. Then \( J(\mathbb{Q}) \cong \mathbb{Z} \oplus (\mathbb{Z}/2\mathbb{Z})^4 \).

**Proof.** The curve \( C \) has bad reduction at 2, 3 and 5. Therefore there are \( 16^4 = 65,536 \) homogeneous spaces to check. The five affine Weierstrass points
on $C$ map to the homogeneous spaces which correspond to the following elements of $D^4$

$$(0,0) - \infty \rightarrow (15,-1,-2,-5)$$
$$(1,0) - \infty \rightarrow (1,-5,-1,-1)$$
$$(2,0) - \infty \rightarrow (2,1,6,-3)$$
$$(5,0) - \infty \rightarrow (5,1,3,-15)$$
$$(6,0) - \infty \rightarrow (6,5,1,1).$$

A test for solutions over $\mathbb{R}$ left $2^{14} = 16,384$ potentially everywhere locally trivial spaces. Tests (mod 2) and (mod 4) reduced the number to 2048. Performing tests (mod 9) on the Type I equations left only 128 spaces, and checking the Type I equations (mod 25) eliminated all but 32 spaces. Sixteen of these spaces correspond to $J[2]$, so the rank of $J(\mathbb{Q})$ is at most one. A short search fortunately found the integral points $(3,6)$ and $(10,120)$ on $C$, with

$$(3,6) - \infty \rightarrow (3,2,1,-2)$$
$$(10,120) - \infty \rightarrow (10,1,2,5).$$

Note that $P = (3,6) - \infty$ is not in the coset of the two-torsion points, so the other 16 spaces correspond to $(P + Q)$, where $Q$ is in $J[2]$. For example, $(10,120) - \infty$ is equal to $(2,0) + (5,0) - 2\infty$ in $J(\mathbb{Q})/2J(\mathbb{Q})$, and using the addition law on $J$ it is quickly discovered that

$$(10,120) - \infty = 2P + (2,0) + (5,0) - 2\infty.$$  

This proves that $J(\mathbb{Q})$ actually has rank 1. To compute the torsion of $J(\mathbb{Q})$, we found via an exhaustive search that

$$|J(\mathbb{F}_p)| = 48, \quad |J(\mathbb{F}_{11})| = 176.$$  

(As the referee notes, there is an easier way to compute $|J(\mathbb{F}_p)|$, since it is just $\frac{1}{2}|C(\mathbb{F}_p)| + \frac{1}{2}|C(\mathbb{F}_p)|^2 - p$. This follows either from comparing the zeta functions of $C$ and $J$ over $\mathbb{F}_p$, or by considering $J$ with the origin blown up as the symmetric product of $C$ with itself). When $p > 2$ is a prime of good reduction, the torsion group of $J(\mathbb{Q})$ injects into $J(\mathbb{F}_p)$. (This follows by considering the formal group on the kernel of reduction of $J$ (mod $p$). For the general result, see [16, p. 135].) Since gcd(48, 176) = 16, the torsion group consists only of the two-torsion points, and $J(\mathbb{Q}) \cong \mathbb{Z} \oplus (\mathbb{Z}/2\mathbb{Z})^4$. 

We do not know whether $P$ is a generator of $J(\mathbb{Q})/J(\mathbb{Q})_{\text{tor}}$. It would be nice to have the theory of heights on Jacobians of curves of genus two worked out explicitly to afford answers to such questions.

**Theorem 3.** Let $C$ be the curve

$$y^2 = x(x-3)(x-4)(x-6)(x-7),$$

and $J$ its Jacobian. Then $J(\mathbb{Q}) \cong (\mathbb{Z}/2\mathbb{Z})^4$.

**Proof:** The curve $C$ has bad reduction at 2, 3 and 7. The affine Weierstrass points on $C$ map to the homogeneous spaces


\[(0, 0) - \infty \rightarrow (14, -3, -1, -6)\]
\[(3, 0) - \infty \rightarrow (3, -1, -1, -3)\]
\[(4, 0) - \infty \rightarrow (1, 1, 6, -2)\]
\[(6, 0) - \infty \rightarrow (6, 3, 2, -1)\]
\[(7, 0) - \infty \rightarrow (7, 1, 3, 1)\].

The test for solutions over \( \mathbf{R} \) left 16,384 spaces. Tests \( (\text{mod} \ 2) \) and \( (\text{mod} \ 4) \) eliminated all but 2048 spaces. Performing tests \( (\text{mod} \ 9) \) on the Type I equations left 384 spaces.

Doing tests \( (\text{mod} \ 7) \) on the Type I equations reduced the number to 80 spaces, or five cosets of \( J[2] \). Testing all the equations \( (\text{mod} \ 3) \) left only two cosets. The representative \( d = (2, 42, 21, -42) \) of the last potentially everywhere locally trivial coset had no solution to the Type I equations \( (\text{mod} \ 49) \). Therefore the Jacobian has no rational points other than the two-torsion points and the curve has no rational points other than its Weierstrass points.

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